* Progress report
  + Completed recorded meeting
  + Kinect Prototyping
    - Have hand skeletons
    - Obtaining joint data
  + Leap Motion Spike
    - Decided to spike into Leap Motion in parallel since more joint data built-in
    - Code made, no sensor yet (struggled to find Mutchler), blocked until available
  + Documentation Updates
    - Modified project plan to reflect change in direction
    - Added a hypothesis
    - Added new requirements to guide our prototype
    - Working on scenarios/overarching architecture doc
  + Note: no code uploaded, blocked on tech issues
* Next steps
  + Continue updating documentation
  + Continue Kinect prototyping
    - Can we get joint details easily?
  + Complete Leap Motion spike and see if the benefits are worthwhile
    - Adit track down Mutchler to unblock this
* Questions/Concerns
  + Link is broken in slides for video upload.
  + Thoughts on new requirements?
  + Thoughts on initial architecture doc?
  + Thoughts on initial scenario(s)?